3KM Detection distance

Counter-UAV-Radar





- 3D mechanical scanning radar, Multi group Sum beam
 Difference beam.
- Improves the "low small slow" target detection capability while reducing the radar's transmit power at the same discovery distance.
- Distinguish between ground and air targets.
- Can work around the clock in harsh environments.
- Multi-point operating frequency, using the same-frequency interference suppression technology to avoid co-channel interference.

Technical parameters

| Model | Radar-YFR-01B | |
|-----------------------------|---|--|
| Overview | | |
| Wave band | Ku | |
| Process technology | chirp | |
| Scan method | Azimuth machine scan+Euler frequency scan | |
| Weight | ≤18kg | |
| Size | 570×375×210(mm) | |
| Power consumption | ≤160W | |
| Basic detection performance | | |
| Display range | 0.075~20km | |
| Azimuth angle | 0°-360° scan | |
| Euler angles | 0°-40° | |
| Measurement dimension | Distance / Azimuth angle / Euler angles / Speed | |
| Detection distance | | |
| Mini UAV (RCS=0.01m²) | 3Km | |
| Detection accuracy | | |
| Distance accuracy | ≤8m | |
| Azimuth accuracy | ≤0.8° | |
| Euler accuracy | ≤0.6° | |
| Resolving power | | |
| Detection Resolving power | ≤20m | |
| Azimuth Resolving power | ≤2.5° | |
| Euler Resolving power | ≤5° | |
| Data process capacity | | |

| Track method | TWS / continuous track |
|-------------------------|------------------------|
| Number of track targets | No less than 200 |
| Map data | Stackable map |



Counter-UAV-System



